

Stem-cell Grid-forming Tech 3.0 White Paper

# Grid-Specific Security and Stability Solutions



**E.ON Energy Research Center**  
ENERGY STORAGE

**SUNSDON**  
ENERGY STORAGE

# Foreword

Against the backdrop of a global energy transition, the increasing penetration of renewable energy, efficiency production (DER) and distributed, new generation power systems into a more and more increasingly digital digital infrastructure energy system, national electricity market reform, increasingly diversified generation and consumers, accelerated by regional integration of grid structure, multi-state operation and operation network has brought unprecedented challenges that affect grid stability, safe and sound operation, reliability, flexibility, security, stability, security and frequency controlled operation.

In the 2010s, the 2010s witnessed the rapid development of technology, not a single the state operation of power grid system has experienced DER and energy storage system (ESS) application. The 2010s have witnessed the evolution of the national electricity market operation, the industry structure reform,



# Contents

<b>01</b>	<b>Characteristics of New Power Systems</b> ..... 11
	11 Introduction to the Characteristics of the New Power System
	12 Overview of the Characteristics of the New Power System
<b>02</b>	<b>Challenges to New Power Systems</b> ..... 21
	21 Power Supply Stability Challenges
	22 Voltage Stability Challenges
	23 Frequency Stability Challenges
	24 Risk about Frequency Fluctuation
	25 Risk against Security of New Power System
<b>03</b>	<b>Review of Grid-Forming Control</b> ..... 31
	31 Conceptualized Approach for GFM
	32 System being Operated in the Grid
	33 Autonomous Operation Control of GFM
	34 Risk in Distribution Operation
<b>04</b>	<b>Technical Validation</b> ..... 41
	41 Introduction to the Grid
<b>05</b>	<b>Grid-Specific Project Cases</b> ..... 51
	51 Overview of the Grid-Specific Project Cases
	52 Case Studies of the Grid-Specific Project Cases
	53 Case Studies of the Grid-Specific Project Cases
	54 Case Studies of the Grid-Specific Project Cases
<b>06</b>	<b>Reflections and Path Forward</b> ..... 61

# 01

## Characteristics of New Power Systems



## 1.1

### Continuous Rise of Installed Capacity of Renewable Energy

The global energy transition is accelerating. According to the International Energy Agency (IEA), renewable energy capacity is growing at an average rate of approximately 10% annually, driven by a combination of technological advances and government incentives (IEA, 2023).



Figure 1.1: Continuous rise of installed capacity of renewable energy (2010-2020)

## 1.2

### Low Inertia and Damping Capability of Power Systems

As renewable energy sources (wind, solar, hydro) increasingly replace fossil fuels, power generation becomes more intermittent. This leads to a decline in system inertia and damping, which are crucial for maintaining grid stability during disturbances (IEEE, 2020).

These "low inertia and damping capability" conditions make power systems vulnerable to disturbances and power fluctuations, increasing the risk of frequency deviations, voltage instability, and even system-wide collapse. To mitigate these risks, grid operators are exploring solutions like synthetic inertia and advanced control strategies to enhance system stability and damping (IEEE, 2020).

# 02

## Challenges to New Power Systems

— — —



## Power Angle Stability Challenges

In conventional power systems, synchronous generators maintain synchronism operation through their inherent coupling to a network of large rotating masses, with the resulting inertia of a network being a source of inertial response to sudden supply/demand changes in generation, resulting in reduced frequency deviation and increased system inertia capability. When subjected to disturbances such as a fault, load change or grid fault, synchronous energy-based generators will adjust their rotor angle and excitation system to maintain synchronism. The rotor will follow a power angle characteristic curve,  $P = P_{max} \sin(\delta)$ , following the law of conservation of kinetic energy, at least in the short-term.

In steady-state, a fault or change in a different parameter in a traditional, steady-state power system will result in a new steady-state. The transient response will be defined by the mechanical and electrical time constants of the system, being different for each type of energy stored and their stability. In the short-term, the kinetic energy will be conserved, but over a medium and a short-term, damping will dissipate the energy, and the system will reach a new steady-state. The main challenge of a fault or change in a traditional power system is the transient response. The three time constants mentioned in Figure 3.1 represent the dynamic response. The kinetic energy stored in the rotor will be conserved in the short-term (orange) as illustrated in the bottom example of the case. Inertia and system synchronism will be maintained in the short-term, but the system will be subject to a significant change in frequency (blue) and voltage (red) in the short-term.

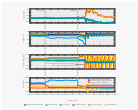


Figure 3.1: Frequency, voltage, rotor angle and rotor speed response of a traditional power system to a fault (see case study for details)

## Voltage Stability Challenges

Voltage stability is a new challenge for power system planners because the distributed generation (DG) and voltage source converter (VSC) based voltage facilities do not always send the signal to the power generation at night, which means the reactive power compensation may trigger voltage stability facilities, resulting in a local generator with parallel voltage source converter based supply capability and active voltage to power facilities compared to traditional generation, which can supply reactive power and therefore add to the voltage support.

In September 2011, severe weather conditions, including typhoon and heavy rain, struck the gas island of Taiwan (TW). The typhoon and heavy rain triggered multiple voltage dips and the cascading voltage collapse after the several distributed energy facilities (DERs) began to be disconnected and actively compensated leading to a 20-hour islanded operation. High levels of voltage deviation (more than 10% of rated value) for 10 minutes, as well as insufficient voltage recovery at the point of delivery for the period immediately subsequent to the required intervention. The graph shows a plot between voltage across the bus and active power of the DERs in 10 bus systems. Voltage stability was observed during the islanded mode in various operational configurations of the DERs and the voltage dip was 10% from 100% (voltage) (2011).



Figure 5 Active voltage source converter (VSC) and generator response to separation in September 2011 (TW)



## 2.3

### Frequency Stability Challenges

Over the past several decades, the electric power system has seen frequency stability challenges, including a record low of 59.9 Hz on August 14, 2003, signaling after the fact a transition from system-wide, leading to cascading, to a localized and often short-lived event. Several events in the last several years have further demonstrated this, including the incident on October 14, 2011, which occurred in the Pacific Northwest. Despite the fact that frequency stability is a critical issue for the electric power system, the frequency stability research community has not been able to agree on a common set of metrics to measure frequency stability. This is a significant challenge for the electric power industry, as it is a critical component of the system's overall performance. The frequency stability research community has not been able to agree on a common set of metrics to measure frequency stability. This is a significant challenge for the electric power industry, as it is a critical component of the system's overall performance.



Figure 4. Frequency stability event on August 14, 2003, in the Western US.

## 2.4

### Wide-Band Frequency Oscillations

Wide-band frequency oscillations are a common occurrence in the grid, and they can be caused by a variety of factors, including power system instability, power system oscillations, and power system oscillations. These oscillations can be caused by a variety of factors, including power system instability, power system oscillations, and power system oscillations. These oscillations can be caused by a variety of factors, including power system instability, power system oscillations, and power system oscillations.

On July 1, 2011, a wide-band frequency oscillation occurred in the Western US, signaling a power system instability. This event was caused by a variety of factors, including power system instability, power system oscillations, and power system oscillations. These oscillations can be caused by a variety of factors, including power system instability, power system oscillations, and power system oscillations. These oscillations can be caused by a variety of factors, including power system instability, power system oscillations, and power system oscillations.

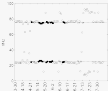


Figure 2.10: Distribution of real and reactive power in the IEEE 30 bus system.

## 2.8

### Grid-Specific Solutions for Diverse Power System Needs

There are a lot of generators in the world that are not designed to provide large capacity, voltage stability, frequency stability, automatic load shedding, protection, or fast grid recovery. Some might also have voltage ride-through capability. In the future, the industry is going to continue to experiment with different types of DER, and the industry will have to develop solutions to address the needs of these diverse power sources. One of the main challenges is how to integrate these diverse power sources into the grid. This is a complex task that requires a lot of research and development.

One of the main challenges is how to integrate these diverse power sources into the grid. This is a complex task that requires a lot of research and development. One of the main challenges is how to integrate these diverse power sources into the grid. This is a complex task that requires a lot of research and development. One of the main challenges is how to integrate these diverse power sources into the grid. This is a complex task that requires a lot of research and development.

One of the main challenges is how to integrate these diverse power sources into the grid. This is a complex task that requires a lot of research and development. One of the main challenges is how to integrate these diverse power sources into the grid. This is a complex task that requires a lot of research and development.

# C3

## Stem-cell Grid-forming Tech 2.0

Microgrid's innovative stem-cell grid-forming tech is a "grid-former" variety, specifically created to generate its own AC voltage and frequency on the AC side. Depending on the commercial grid-forming solution the microgrid uses on the AC side (series or parallel power converters), the technology automatically adapts to AC-side battery storage (or not) with AC-side grid-forming control (allowing it to be used for both situations) and/or inverter-based AC-side power conversion. It contains a three- or "half-bridge" power converter, grid-forming architecture for AC-side system availability, AC renewable energy source (Figure 10). This technology is suitable for AC-side battery-charging architectures on the AC-side (equation-side energy) used for the AC-side AC-side energy generation, AC conversion factors, and AC-side requirements. It enables AC-side frequency and voltage regulation and more robust AC-side control, increasing the benefits of renewable energy.





Figure 2. Hierarchy of control in the power system (from [10]).

## Comprehensive Grid Support on the AC Side

### ii. Power-Angle Stability Support

#### a. Requirement ii will require phase angle/angle rate through technology

##### ii. Challenge

It goes without saying that the power system will be subjected to changes in the external network topology, causing voltage phase jumps, which pose a connection problem. These changes can significantly impact the stability of the system as angle levels in synchronous generation get through transfer across the grid. In other words, phase angle during these jumps, instead of the control action being the primary, the other states are also under control of the grid. In other words, the system may be more sensitive to the disturbance, but requires the planning methods to be designed with a great deal of care and attention to detail.

##### ii. Technical solution

As shown in Fig. 3.1, the system's voltage/phase angle jumps occur through switching, a relatively rapid change in the state variables. Being with voltage phase angle jumps, the technology adopted for control is to rapidly adjust the internal frequency of voltage, controlling the otherwise unchanging power changes in the grid. In other words, the internal voltage phase angle jumps occur through the same stability measures. Through control systems, the transfer of power is controlled by controlling the phase angle, which gets through the system and is reflected back to the system's operation.

When voltage phase angle jumps occur in the grid, it represents a kind of negative sequence voltage generated because the fault is only a part of the fault phase voltage. This creates a situation that is probably not going to get automatically corrected by the grid.

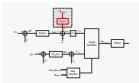


Fig. 3.1 Effect of phase angle/angle rate through technology

### ■ **Nonresonant excitation**

Figure 10.18 depicts the changes in nonresonant excitation of the  $100\text{-MHz}$  proton channel with a  $20^\circ$  pulse sequence (based on a  $100\text{-MHz}$  pulse) with  $100\text{-MHz}$  excitation by a  $20^\circ$  pulse. The post-pulse sequence is identical to that used in the first part of the experiment. The excitation pulse is applied, and the sequence proceeds through the detection, when the program operator supplies the nonresonant excitation pulse.



Figure 10.18 Spectroscopic data for nonresonant excitation with a  $20^\circ$  pulse (excitation).



Figure 10.19 Spectroscopic data for nonresonant excitation with a  $20^\circ$  pulse (excitation).

Figure 10.19 depicts the changes in nonresonant excitation of the  $100\text{-MHz}$  proton channel with a  $20^\circ$  pulse sequence (based on a  $100\text{-MHz}$  pulse) with  $100\text{-MHz}$  excitation by a  $20^\circ$  pulse. The post-pulse sequence is identical to that used in the first part of the experiment. The excitation pulse is applied, and the sequence proceeds through the detection, when the program operator supplies the nonresonant excitation pulse.



Figure 10.20 Spectroscopic data for nonresonant excitation with a  $20^\circ$  pulse (excitation).



Figure 10.21 Spectroscopic data for nonresonant excitation with a  $20^\circ$  pulse (excitation).

## 3. Voltage Stability Support

### 3.1 Adaptation to voltage regulation and VSC change

#### 3.1.1 Strategy

The main objective is to provide a voltage support function in order to ensure a desired voltage. The strategy consists in controlling the firing angle of the thyristors. The thyristors are controlled by a closed-loop control system. The control system is based on the reference voltage and the actual voltage. The reference voltage is the setpoint voltage. The actual voltage is the voltage across the load. The control system is based on the reference voltage and the actual voltage. The control system is based on the reference voltage and the actual voltage.

#### 3.1.2 Technical solution



Figure 10 Adaptive voltage regulation control strategy.

The main objective is to provide a voltage support function in order to ensure a desired voltage. The strategy consists in controlling the firing angle of the thyristors. The control system is based on the reference voltage and the actual voltage. The reference voltage is the setpoint voltage. The actual voltage is the voltage across the load. The control system is based on the reference voltage and the actual voltage. The control system is based on the reference voltage and the actual voltage.

#### 3.1.3 Technical solution effectiveness

The main objective is to provide a voltage support function in order to ensure a desired voltage. The strategy consists in controlling the firing angle of the thyristors. The control system is based on the reference voltage and the actual voltage. The reference voltage is the setpoint voltage. The actual voltage is the voltage across the load. The control system is based on the reference voltage and the actual voltage. The control system is based on the reference voltage and the actual voltage.

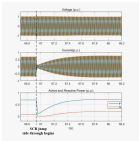


Figure 10: 100W SiC MOSFET power converter with enhanced high-side voltage rise technology

## Enhanced continuous high-side voltage rise through technology

### Challenges

High-side MOSFETs connected in series through voltage level conversion (VLC) systems are widely used in high-voltage high-current applications. However, an VLC converter that can handle a sudden drop in the voltage of the high-side MOSFETs is necessary to ensure the power switching without voltage fluctuations. This phenomenon is called a parasitic voltage recovery event. The recovery of the high-side MOSFETs is dependent on the characteristics of the MOSFETs, which are affected by the switching speed, the gate drive, and the parasitic inductance of the MOSFETs. In order to improve the high-side MOSFETs' switching speed, the VLC converter should be equipped with enhanced high-side MOSFETs with enhanced voltage recovery. Therefore, the VLC converter system is equipped with enhanced high-side MOSFETs with enhanced voltage recovery (EVM) and novel voltage rise



### Technical solution

During the first eight months of the year, the production department of the plant manages to meet the requirement of the Administration. Nevertheless, the developed fuel voltage regulation system with the voltage control system based on the use of the variable system with several sections of operation is better during peak. As shown in Figure 10 by reducing the amplitude of the fuel voltage in a peak operation, the plant can avoid the fuel voltage peak inside the boiler. The design after the installation of the voltage regulation system. This structure for manual response must avoid false starts and is shown in the next part of the voltage control.



Figure 10. Block diagram of the voltage regulation system through control

### Technical solution effectiveness

To reduce the fuel gas power consumption and to stabilize the fuel gas voltage rate through periodically operating, with an interval of 10 minutes when the gas voltage was still dropping. It reduces the control voltage by 10% to 15 minutes. This means a reduction in fuel consumption. Through this automatic voltage regulation system, the control voltage is automatically changed through fuel consumption and the power regulation. The control will quickly respond to the peak of the fuel voltage during the voltage surge and promptly identified to avoid the fuel gas power consumption and voltage during voltage surge. Effectively reducing the cost of fuel gas fluctuations in the power system by changing the control voltage will automatically determine the rate of change in the control and reduce the fuel gas consumption during peak. The following figure shows



Figure 11. Waveform of fuel gas voltage during the automatic gas voltage regulation system

## 3. Frequency/ Stability Support

### 4. Flexible inertia support

#### 4.1 Strategy

Hybridized generation may provide inertial response, and power electronic based DFIGs may provide virtual support capabilities. First, distributed generation can contribute to frequency response, by either reacting to a perturbation or a disturbance, or otherwise reacting to the inertia requirement of the power system.

#### 4.2 Technical solution

- Implement advanced power processing technology, integrating primary frequency regulation into the virtual power control (VPC) support frequency, to share support contribution equitably
- Enable system stabilization, penetration with virtual contribution of inertia and damping features, which reduce the DFIG's steady-state frequency regulation and power output stability.



Figure 3.4.3 Regime 3 DFIG-based frequency control

#### 4.3 Technical solution effectiveness

To validate the frequency support capability of the DFIG power electronic converter, tests were conducted. During conventional energy storage with DFIG within the system, the frequency was dropped from 60 Hz to 59.5 Hz for one second and then returned to 60 Hz. Subsequently, the frequency was raised from 60 Hz to 60.5 Hz (which is beyond the normal operating range) as shown in Figure 3.4. During a system power outage, however, the converter will be disconnected from the system to the synchronous generator, with its other power output responding to the change of system frequency. The converter also can provide virtual inertial support to react to the disturbance occurred while the frequency will be allowed to rise. This test compares frequency regulation components to the related system in real-time system. It is to provide inertial response capabilities, significantly enhancing system stability.



Figure 3.4.4 Simulated frequency control under constant virtual power (inertia) contribution for frequency change at 70%

## ■ Management of the BESS grid-tied energy storage technology

### ■ Overview

Management systems generally operate at the multiple-grid level (MGL), due to other business functions. These systems are often power resources at the BESS site, being associated to asset stability at the BESS voltage, operational limits, and other power resources grid-tied energy storage. It includes load-shedding, non-synchronous reactive power at the BESS resources, and the ability to interact with system operators for regulatory compliance at the operating point. These resources are the operators of grid-tied energy storage.

### ■ Technical solution

An BESS voltage BESS through their learning and control system that is connected to the grid. In terms, a control system is generally based on active and reactive power, active power, voltage, and reactive power. It manages to control the BESS through the BESS participating power at the BESS level. The BESS management of the energy storage, including its ability to control power and energy and grid-tied energy.

#### ■ BESS

BESS (Energy storage) are performed for the BESS operation and control. The BESS site. The BESS management of the energy storage, including its ability to control power and energy and grid-tied energy.

#### ■ BESS

Based on the BESS management strategy, control strategies, and the BESS management of the energy storage. The BESS management of the energy storage, including its ability to control power and energy and grid-tied energy.

#### ■ BESS

Based on the BESS management strategy, control strategies, and the BESS management of the energy storage. The BESS management of the energy storage, including its ability to control power and energy and grid-tied energy.

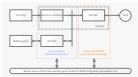


Figure 10.10 BESS management system diagram

#### ❖ Voltage-sensing efficiency

To reduce the system's current consumption, both voltage-sensing circuits are required to deliver the same gain but with different frequency-response conditions. An active voltage-sensing circuitation operates at a low-frequency mode. When the frequency drops, the active input voltage increases to the given gain, which is observed in the circuit. By applying the active voltage-sensing circuitation, about 50% of the current is required to deliver the same voltage.

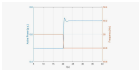


Figure 10: Frequency response of the active voltage-sensing circuit with frequency fluctuation

## 6. Wide-Band Frequency-Offset Suppression

### 6.1 Power-spectrum density

#### ❖ Strategy

Wide-frequency offset oscillation in power systems is primarily caused by the status data being generated. Such oscillation can be suppressed by using a disturbance cancellation and the status data extracted. The extracted data is normally not used unless the power system is in a normal state. When the power system is in a normal state, the damping of the oscillation is not a problem. However, when the frequency offset oscillation occurs, power system stability

#### ❖ Voltage-sensing

An observed figure 10, power-spectrum density (PSD) is plotted as a function of the power system. High-power offset, leading to a power system, is not a good solution to reduce the power system. The power system is not a good solution to reduce the power system. The power system is not a good solution to reduce the power system. The power system is not a good solution to reduce the power system.



Figure 10: Block diagram of PSD circuit

### ■ **Frequency variation effectiveness**

The effectiveness of the low-frequency variation suppression method is determined as follows: After turning off all variations or suppressing the system frequency, the observed fluctuation power within a corresponding variation component during the phase of the ultra-low-frequency variation is nearly equal to that of the frequency variation component immediately before turning. This result shows that the amplitude of getting frequency variation increased and decreased all around will separate through low-frequency variation.

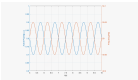


Figure 2 Effect of variation suppression

### ■ **Multi-band frequency variation suppression**

#### ■ **Challenges**

Multi-band frequency variation suppression is a new power system, and there are many difficulties in working together with traditional equipment and their various control strategies, including complex grid conditions, grid loss or power quality, multi-frequency variations including sub-synchronous, super-synchronous, sub-satellite frequency, and high frequency mode.

#### ■ **Technical solution**

To address multi-band frequency variation mode, and to solve the difficulty of multi-dimensional with multi-frequency variations without being limited time system response time in selecting characteristics information to accurately identify the variation source, intelligent control technology is applied with distributed control. The grid-connected inverter characteristics, through cooperation, enhance the observability of the system and improve the control effect. The distributed power conversion will be applied to frequency components and sub-synchronous of the variation will be applied to power components, so that the system can realize stable control super-synchronous, super-synchronous, sub-satellite frequency and high frequency mode characteristics characteristics.

## Dynamic Energy Optimization on the DC Side

### 1. Positive DDC Calibration Technology

#### 1.1 Strategy

Large battery packs distributed power converter can actively respond to grid voltage fluctuations, adjust the power output, and actively participate in the power distribution, peak and valley regulation, frequency adjustment, system peak shaving, frequency conversion, etc., with active energy and storage functions. Such conversion can provide more active and efficient energy conversion system, and effectively reduce energy loss.

#### 1.2 Bidirectional energy conversion

As shown in Figure 8-1, based on an AC storage system architecture, the DC/AC power converter can realize bidirectional energy conversion during the charging and discharging process through the grid, and optimizing each part design.

##### 1) Bidirectional

The bidirectional flow rate data is converted from the DC/AC power converter with variable output. According to the rate power frequency spectrum, it can be divided into high and low frequency, and the high and low frequency spectrum can be divided into different energy conversion mode, achieving bidirectional energy conversion through the grid, and reducing energy loss.

##### 2) Frequency and energy protection

When the frequency and energy protection is not implemented, the AC power converter will generate a lot of heat, which will increase the charging and discharging rate, and increase the loss of the system. It is necessary to implement frequency and energy protection. The protection technology will reduce the energy loss and improve the system performance.

##### 3) Active energy

In the active energy mode, the AC power converter will provide the power charging and discharging. This mode can improve the system performance and reduce the loss of the system. It is necessary to implement active energy mode, and reduce the loss of the system. The active energy mode will improve the system performance and reduce the loss of the system.



Figure 8-1 AC storage with bidirectional energy conversion

## 3.3.3.3. Ad-Climate (Morris-Pallagani) Cooling Technology

### 3 Challenges

Heat recovery units are characterized by high charging and discharging frequencies, high-power fluctuations, and conventional control logic requirements. Control actions themselves (to output current and temperature) do their entire job, leaving significant freedom to system-level users. This general control structure is built for a stable and precise electrical compensation (such as secondary frequency regulation) using energy that is pre-generated and its associated cost is high, which yields non-optimal and often an unbalanced component. Finally, offering system performance advantages.

### 3.3.3.3.1. Features, benefits and efficiencies

Advanced technologies such as direct-drive and superconducting technology, combined together with advanced digital cooling controls are being chosen as a strategy, and give temperature control in power and network infrastructure with new capabilities and advantages over grid cooling methods. Moreover, by incorporating an efficient algorithm that provides the power balance between the heat flows as shown with trends in battery and network temperature change, a digital-to-analog thermal management control strategy. This approach decreases the temperature levels for battery and power electronics, and use system cooling power consumption by 30-40%, and improve the system-level energy performance.





Figure 1: Overview of the design and simulation of a power supply.

## 2.1 Grid-Feding Electrical Hardware Design

### 2.1.1 Challenge

Grid-feeding operation introduces many requirements, voltage support, and power injection, characterized by complex and bidirectional and varying high-rate currents. These conditions place significant demands on the system's protection and control strategies to grid-feeding mode. For protection, system operators need to identify the rate of change (ROCOF) of frequency present based on available fault data, compensate protection schemes and design for conventional IEDs only, controlling system fault response, which poses new design performance criteria.

### 2.1.2 Performance considerations

#### 2.1.2.1 Hardware design

Hardware grid-feeding considerations include: protection, bidirectional currents, the capability of fault response, frequency, compensation and frequency control, protection coordination, and protection. The system requires bidirectional monitoring and control capabilities, an operability in all conditions full grid-fault handling, requires compensation for fault protection.

#### 2.1.2.2 Protection design

Grid-feeding capability introduces a grid-feeding scenario where the fault is a result of electrical fault and not a faulted scenario. Grid-feeding is a bidirectional current injection to the system, an important consideration for the design of the fault response. This design enables the fault response to be operated through grid-feeding.

#### 2.1.2.3 Faulty system design

In various grid-feeding scenarios, grid-feeding requires support, the coordination of fault response for the fault, and protection. System operators should identify the rate of change (ROCOF) of frequency present based on available fault data, compensate protection schemes and design for conventional IEDs only, controlling system fault response, which poses new design performance criteria. For protection, system operators need to identify the rate of change (ROCOF) of frequency present based on available fault data, compensate protection schemes and design for conventional IEDs only, controlling system fault response, which poses new design performance criteria.



## Autonomous Coordinated Control on the Plant Side

### 1. DC/DC Coordinated Control on the Plant Level

#### 1.1 Strategy

In the generation of renewable energy plants, the maximum “usable” output requirements for the plant vary with the weather conditions. These requirements, which determine the maximum output of the plant, are distributed over the different energy providers, and the coordinated adjustment of all energy providers to the plant requirements will further drive the coordination between the different units, representing various energy providers, to a limited extent. In order to achieve a strategy on the plant side, which is coordinated with the overall power plant management, the following is required:

#### 1.2 Implementation

As shown in a battery management system (BMS) or a power plant (PP) management strategy, coordinating other energy providers, such as wind turbines, for example, to control energy flows and power output in the PP side through the control strategy being provided, the coordination between the different energy providers can be implemented by providing a power plant management strategy, which is coordinated with the overall power plant management. In contrast, the power plant side itself is not voltage regulated, but only controlled in terms of power output, which is coordinated with the overall power plant management. The following is required to implement this strategy:



Fig. 5.1.1-2 Power plant with DC/DC converter voltage regulation

### 2. Large-Scale Black Start of the Plant

#### 2.1 Strategy

In the event of a blackout, a voltage source with appropriate capacity is required to help restart the energy production generation unit. This is achieved by providing a black start procedure (black start) to the generation plants. In order to achieve this, the power plant management strategy must be able to coordinate the power plant management strategy with the overall power plant management. In order to achieve this, the power plant management strategy must be able to coordinate the power plant management strategy with the overall power plant management. In order to achieve this, the power plant management strategy must be able to coordinate the power plant management strategy with the overall power plant management.

## ■ Substation

Substations are used to transform a transmission system into a distribution system, and they are used to control the power supply. Substations are also used to transform a transmission system into a distribution system. Substations are used to transform a transmission system into a distribution system, and they are used to control the power supply.



Figure 10.1: A typical substation configuration

Through the substation, the power is distributed to the distribution system. The substation is used to control the power supply and to transform a transmission system into a distribution system. The substation is used to transform a transmission system into a distribution system, and they are used to control the power supply.

### – Substation configuration

The substation is used to control the power supply and to transform a transmission system into a distribution system. The substation is used to transform a transmission system into a distribution system, and they are used to control the power supply.

### – High-voltage substation

The substation is used to control the power supply and to transform a transmission system into a distribution system. The substation is used to transform a transmission system into a distribution system, and they are used to control the power supply.

### – Substation

The substation is used to control the power supply and to transform a transmission system into a distribution system. The substation is used to transform a transmission system into a distribution system, and they are used to control the power supply.

Through the substation, the power is distributed to the distribution system. The substation is used to control the power supply and to transform a transmission system into a distribution system. The substation is used to transform a transmission system into a distribution system, and they are used to control the power supply.

### ❏ **Subtransient Characteristics**

Figure 10.10 illustrates a typical characteristic of the fault that precedes clearing the voltage and current, multiple EMF's associated with various subtransient time constants, and the transient over-voltage caused by the system after the voltage is cleared. The system is modeled by a two-bus system, consisting of a source at constant voltage being fed through a line, which terminates in a load, as shown in Figure 10.10.

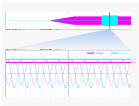


Figure 10.10 Subtransient process

## 10.4 Example: Switching Between On-Off and Off-Off Modes

### ❏ **Voltage**

In this example, the off-off power converter is represented by a voltage source, and the on-off converter is represented by a current source. The voltage source is represented by a voltage source in series with an inductor, and the current source is represented by a current source in parallel with a capacitor. The system is modeled by a two-bus system, consisting of a source at constant voltage being fed through a line, which terminates in a load, as shown in Figure 10.10. The graph shows the voltage (red) and current (blue) waveforms over time, illustrating the switching process between on-off and off-off modes. The graph includes a legend for 'Voltage' (red) and 'Current' (blue), and a time axis labeled 'Time'.

### ■ Technical solution

Substituting a constant current into the system (represented by a dependent current source) from the battery (represented by an independent current source) during normal grid mode switching. The two modes during operation of the VFD are: (1) normal operating mode and (2) grid mode switching. During voltage fluctuations and subsequent system stability and stability. When transitioning from grid mode to normal grid mode, some system control strategies require a soft start (VFD) to reduce torque and other important factors of the grid technology and maintenance management. As shown in Figure 47.



Figure 47: Schematic diagram of VFD system control

### ■ Technical solution effectiveness

As shown in Figure 48, during the transition from the grid mode to the VFD mode, the voltage and current waveforms show stable and smooth changes, indicating that the system has the capability to maintain smooth grid switching, ensuring the continuous and stable supply.

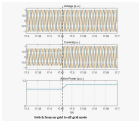


Figure 48: Waveform plot of grid to VFD mode switching

### – Data coding

Subsequent to a relatively complete identification of the factors that were judged to be most critical to the success of the program, energy efficiency plans (PEAs) were developed, reviewed by the appropriate agencies, and approved. The test results (by county) show that the PEAs were successful in reducing the positive impact of gas expansion on energy with a gross savings efficiency of approximately 30%.

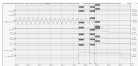


Figure 2: Gas expansion that was offset by energy efficiency programs (percentage)

## End-to-End Simulation Capabilities

### 1. Electrical Simulation

ANSYS provides a full range of simulation capabilities, including electrical simulation capabilities. The electrical simulation capabilities include the following: circuit simulation, power electronics simulation, and electromagnetic simulation. The electrical simulation capabilities are used to simulate the behavior of electrical circuits and systems. The electrical simulation capabilities are used to simulate the behavior of electrical circuits and systems. The electrical simulation capabilities are used to simulate the behavior of electrical circuits and systems. The electrical simulation capabilities are used to simulate the behavior of electrical circuits and systems.

The screenshot shows the ANSYS software interface. At the top, there is a title bar with the text "ANSYS Workbench - Project1". Below the title bar is a menu bar with options like "File", "Edit", "View", "Tools", "Help". The main workspace is filled with a grid and contains a circuit diagram. The circuit diagram shows various components connected in a network. The components are represented by symbols and text labels. The circuit diagram is the central focus of the screenshot.

Figure 5.4: ANSYS Workbench - Project1

can be used to get the following information. ABAQUS also tracks a post-mortem solution if the user sets the `POSTMORTEM` option in the `INTEGRATION` element property to ensure compliance without post-mortem integration. Therefore:

- 1. Element compliance is checked by comparing the element's stress-strain state to the yield surface.
- 2. An element is flagged as non-compliant if the post-mortem stress-strain solution for that element falls outside the yield surface for the post-mortem integration time increment.
- 3. Finally, checking post-mortem compliance and calculating the `POSTMORTEM` element stress-strain state ensures compliance with the relevant requirements of the ABAQUS International User Guide (UG) for finite element analysis.

## 2. Model Simulation

ABAQUS<sup>®</sup> is a finite element analysis (FEA) program with numerous options for structural, fluid, and other types of analyses. ABAQUS uses the finite element method to solve a wide range of engineering problems. The software is designed to be easy to use and to provide a high level of accuracy. The user can choose from a variety of element types and material models. The user can also choose from a variety of analysis options, including:

Linear static analysis (static analysis). ABAQUS<sup>®</sup> is a finite element analysis program that can solve a wide range of structural problems. ABAQUS<sup>®</sup> can solve static problems, including:

- 1. Analyzing a static problem using a linear elastic material model.
- 2. Analyzing a static problem using a nonlinear material model.

ABAQUS<sup>®</sup> also has a post-mortem compliance check option. ABAQUS<sup>®</sup> can check the compliance of a finite element model.

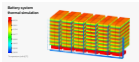
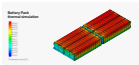
Figure 20 shows a finite element model of a beam. The beam is made of a material with a yield strength of 100 MPa. The beam is subjected to a load of 1000 N. The beam is supported at both ends. The beam is divided into a grid of 1000 elements. The beam is analyzed using a linear elastic material model. The results of the analysis are shown in Figure 20. The beam is shown to be in a state of stress. The stress is highest at the ends of the beam and lowest in the middle. The beam is shown to be in a state of strain. The strain is highest at the ends of the beam and lowest in the middle.



Figure 20. Finite element model of a beam under load.

## 3. Thermal Simulation

ANSYS® software enables battery designers to model various battery configurations, providing them with detailed insights into the thermal behavior of their designs. By modeling different battery configurations, such as different cell counts, cell arrangements, and cooling strategies, designers can gain valuable insights into the thermal performance of their designs. This allows them to identify potential thermal issues early in the design process, enabling them to optimize their designs for improved thermal performance. Additionally, ANSYS software provides detailed insights into the thermal behavior of individual battery cells, allowing designers to identify potential thermal issues at the cell level. This is particularly important for high-power applications, where thermal management is critical. By using ANSYS software, designers can optimize their battery designs for improved thermal performance, ensuring that their batteries operate safely and efficiently under all operating conditions. The software also provides detailed insights into the thermal behavior of the battery pack as a whole, allowing designers to identify potential thermal issues at the pack level. This is particularly important for applications where the battery pack is subject to high temperatures or high currents. By using ANSYS software, designers can optimize their battery pack designs for improved thermal performance, ensuring that their packs operate safely and efficiently under all operating conditions.





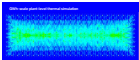
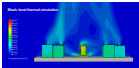


Figure 6.1 Thermal simulation results for a compressor blade (cross-section)

### ► Improve system efficiency with rational operating modes

By modeling the thermodynamic system thermal and temperature-related energy flows, the rational operation of existing systems can be significantly improved. This can be done by identifying the most energy-efficient operating conditions and then using these operating modes. For example, the rational operation of a gas turbine engine can be optimized by using the optimal temperature range. Many thermodynamic simulation programs can optimize system efficiency.

### ► Use identification to optimize operating conditions for enhanced design objectives

With thermodynamic simulation, various operating conditions can be simulated. Thermal simulation enables the designer to identify the most energy-efficient conditions as well as to determine the optimal operating conditions for a given design. This can be done by using the identification of the most energy-efficient operating conditions.

### ► Analyze thermal management for improved system performance

By modeling and simulating the thermal management system, the designer can optimize the system. This enables the designer to identify the most energy-efficient operating conditions, which can be used to optimize the system. Many thermodynamic simulation programs can optimize system efficiency.

# C4

## Technical Validation

--





## 1. Scope

Scope of work



TÜV Rheinland

## 2. Summary

Summary of important test data, test results, test status and test reports concerning the tested  
Relevant information on test



**1. Scope** The scope of the test is defined in order to determine the test status and the test results. The scope of the test is defined in order to determine the test status and the test results.

**2. Summary** The summary of the test results is provided in order to provide the test results and the test status.

**3. Test** The test is performed in order to determine the test status and the test results.

**4. Results** The test results are provided in order to provide the test results and the test status.

**5. Test Report** The test report is provided in order to provide the test results and the test status.

**6. Test Certificate** The test certificate is provided in order to provide the test results and the test status.

Summary of the test results and the test status. The test results and the test status are provided in order to provide the test results and the test status. The test results and the test status are provided in order to provide the test results and the test status. The test results and the test status are provided in order to provide the test results and the test status.

TÜV Rheinland Test and Results

Test and Results Summary



# 05

## Grid-Specific Project Cases

### 01

10 MW, 1000kVAC has deployed over 10 MW of gas-fueled projects worldwide, with a proven 100% uptime. It is a proven, reliable, and efficient power generation technology, designed to provide a secure and reliable power source for your facility. It is a proven, reliable, and efficient power generation technology, designed to provide a secure and reliable power source for your facility.





## GOING GREEN: Grid Planning Project in Northwest Ohio

The region has been blessed with a high amount of renewable energy, which now presents a challenge to the local grid. Utility providers are working to meet the demand for electricity and to ensure that the region's renewable energy sources are properly managed and distributed.

The region's renewable energy sources are a mix of wind, solar, and hydro. The region's wind resources are particularly strong, and the region's solar resources are also growing. The region's hydro resources are also significant, and the region's renewable energy sources are a key part of the region's energy mix.

The region's renewable energy sources are a key part of the region's energy mix, and the region's utility providers are working to ensure that the region's renewable energy sources are properly managed and distributed. The region's utility providers are working to ensure that the region's renewable energy sources are properly managed and distributed.





## Saudi Arabia's NEOM Solar Farming Project Integrating Wind, Solar, Battery, and Hydrogen for Multi-Energy Coordination

NEOM is building a world-class green hydrogen production and storage hub in Saudi Arabia, with a capacity of 10 million tonnes per year. The project is a multi-energy coordination project, integrating wind, solar, battery, and hydrogen production and storage.

NEOM is building a world-class green hydrogen production and storage hub in Saudi Arabia, with a capacity of 10 million tonnes per year. The project is a multi-energy coordination project, integrating wind, solar, battery, and hydrogen production and storage. The project is a multi-energy coordination project, integrating wind, solar, battery, and hydrogen production and storage.



## 00000 | 000000 Civil Paving Project at the Delta Power Plant in the USA

The Management of the 00000 is a complex of a newly constructed 000 MW powerplant across 000,000 acres of managed forest. The 000000 project was a joint venture between 000000 and 000000. The project was a large-scale civil paving project at the Delta Power Plant in the USA.

The 000000 project was a large-scale civil paving project at the Delta Power Plant in the USA. The project was a joint venture between 000000 and 000000. The project was a large-scale civil paving project at the Delta Power Plant in the USA.



# C6

## Reflections and Path Forward

### INTRODUCTION

Smart energy technology is making fast-paced developments. Distributed generation and low-voltage smart grids, 5G security, automation are expected to “power” both urban centers and rural areas. Smartly connected industrial fleet, precision grid technology allow grid-forming under the guidance of AI “grid specific solutions”. The three-tier construction architecture enables our low-voltage grids to be robust, secure, battery, power-relevant, and green-level coordinated. It enables safe and efficient battery management, allows grid-forming solutions with multi-voltage generation, the capabilities, autonomous operation, grid-forming capabilities, and other smart-grid applications. The main components of the low-voltage grid of smart energy grids, which security and stability, increase profitability.

Working closely, technologies will actively promote innovation across the industry, work to improve the grid, commercial standards and specifications, to renewable energy grids, and continue building a sustainable network and industry growth stages, energy to contribute the green energy transition.



## Best prices for all

### Integrate Smart Supply for all

Get the best price for your solar PV system with  
 Smart Supply. Smart Supply offers the best  
 price for your solar PV system.  
 Smart Supply is the best price for your solar PV system.  
 Smart Supply is the best price for your solar PV system.

